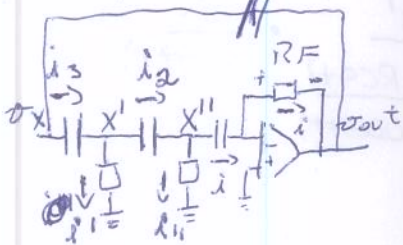


Exemplo 13.5 - Sedra



≠ Sem realimentação

$$\rightarrow v_{out} = -R_F \cdot i$$

$$\rightarrow i = \frac{v_{X''}}{1/SC}$$

$$\rightarrow i_{11} = \frac{v_{X''}}{R}$$

$$v_{out} = -R_F v_{X''} \cdot SC$$

$$\rightarrow i_2 = i + i'' = v_{X''} SC + \frac{v_{X''}}{R} = v_{X''} \left(SC + \frac{1}{R} \right)$$

$$\rightarrow v_{X'} = v_{X''} + i_2 \cdot \frac{1}{SC} = v_{X''} + v_{X''} \left(SC + \frac{1}{R} \right) \cdot \frac{1}{SC} = v_{X''} \left(2 + \frac{1}{RCS} \right)$$

$$\rightarrow i_1 = \frac{v_{X'}}{R} = \frac{v_{X''}}{R} \left(2 + \frac{1}{RCS} \right)$$

$$\bullet i_3 = i_1 + i_2 = \frac{v_{X''}}{R} \left(2 + \frac{1}{RCS} \right) + v_{X''} \left(SC + \frac{1}{R} \right)$$

$$i_3 = v_{X''} \cdot \left[\left(\frac{2}{R} + \frac{1}{R^2CS} \right) + \left(SC + \frac{1}{R} \right) \right]$$

$$i_3 = v_{X''} \cdot \left[\frac{3}{R} + \frac{1}{R^2} + SC \right]$$

$$\bullet v_X = v_{X'} + i_3 \cdot \frac{1}{SC} = v_{X''} \left(2 + \frac{1}{RCS} \right) + v_{X''} \left[\frac{2}{RSC} + \frac{1}{R^2SC} + \left(1 + \frac{1}{RCS} \right) \right]$$

$$v_X = v_{X''} \cdot \left[2 + \frac{1}{RCS} + \frac{2}{RSC} + \frac{1}{R^2SC} + \left(1 + \frac{1}{RCS} \right) \right]$$

$$v_{X''} = \frac{v_X}{\left[2 + \frac{3}{R} + \frac{1}{R^2} + SC \left(1 + \frac{1}{R} \right) \right]} = \frac{v_X}{\frac{1}{R^2CS^2} + \frac{4}{RCS} + 3}$$

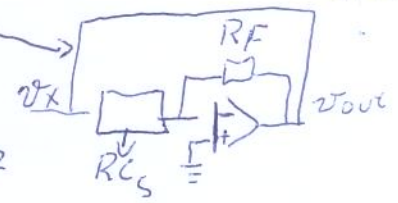
$$v_{out} = -R_F \frac{v_X SC}{2 + \frac{3}{R} + \frac{1}{R^2} + SC \left(1 + \frac{1}{R} \right)} = -R_F \cdot \frac{v_X}{\frac{1}{R^2CS^2} + \frac{4}{RCS} + 3} \cdot SC$$

$$v_{out} = \frac{-R_F v_X SC^2 \cdot R}{\frac{1}{R^2CS} + \frac{4}{R} + 3SC \cdot R} = \frac{-R_F S^2 C^2 R v_X}{\frac{1}{RCS} + 4 + 3RCS} = \frac{R_F R C^2 \omega^2 v}{\frac{4 + j}{RCS} + 3RCj\omega}$$

$A_{v0} = \pm \frac{R_F R C^2 \omega^2}{1 + j(3RC\omega + \frac{1}{RC\omega})}$

13.6 $A(s) \rightarrow$ função em malha aberta $\Rightarrow A(s) = A_0 = \frac{R_F R C^2 \omega^2}{4 + j(3RC\omega - \frac{1}{\omega RC})}$

$B(s) \rightarrow$ Realimentação $\Rightarrow B(s) = 1$



$\therefore L(s) = A(s) \cdot B(s) = \frac{R_F R C^2 \omega^2}{4 + j(3RC\omega - \frac{1}{\omega RC})}$

$|L(j\omega_0)| = 0 \Rightarrow 3RC\omega_0 = \frac{1}{\omega_0 RC} \Rightarrow \omega_0 = \sqrt{\frac{1}{3R^2C^2}}$
 \downarrow
 $10^4 \rightarrow 16 \cdot 10^{-9}$

$\div 2\pi$ $\left(\begin{array}{l} \omega_0 = 3.608,4 \text{ rad/s} \\ f_0 = 574,3 \text{ Hz} \end{array} \right)$

$|L(j\omega_0)| = 1 \Rightarrow \frac{R_F \cdot R C^2 \cdot \omega_0^2}{4} = 1$

$R_F = \frac{4}{R \cdot C^2 \cdot \omega_0^2} \Rightarrow (R_F = 120k\Omega)$